

Resurrecting Equi-Spaced Polynomial Interpolation

A distribution agnostic approach

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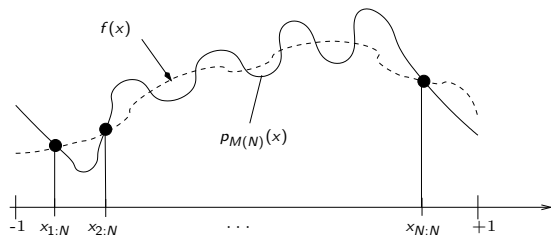
Fast Algorithms

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Interpolation



Given

- ▶ N points $-1 \leq x_{1;N} < x_{2;N} < \dots < x_{N;N} \leq 1$,
- ▶ samples of a function $f: f(x_{i;N})$,

find a polynomial $p_{M(N)}$ of degree $M(N)$ such that

- ▶ it **interpolates**: $p_{M(N)}(x_{i;N}) = f(x_{i;N})$, for $1 \leq i \leq N$,
- ▶ and **approximates**: $\lim_{N \uparrow \infty} p_{M(N)}(x) = f(x)$,

if x is a limit point of the x_N .

$$M(N) = N - 1$$

- ▶ Picking a polynomial of degree $N - 1$ is the most straightforward.
- ▶ Unfortunately it lacks the **approximation** property in most situations.
- ▶ **Runge's phenomenon**
 - ▶ If $x_{i;N}$ is equi-spaced
 - ▶ $f(x) = (1 + 100x^2)^{-1}$

Then p_{N-1} **diverges** from f . **Note:** f is analytic on the real line.

- ▶ **Marcinkiewicz** and **Grünwald**. If the $x_{i;N}$ are the zeros of the N -th degree Chebyshev polynomial, then there is a continuous f for which p_{N-1} diverges. Such an f has a modulus of continuity ω that does **not** satisfy the Dini-Lipschitz condition

$$\lim_{N \uparrow \infty} \omega \left(\frac{1}{N} \right) \log N = 0.$$

Current Practice

If possible use Chebyshev zeros.

- ▶ Current sampling technology prefers equi-spaced.
- ▶ In non-rectangular domains optimal sample point placement is more difficult.

Solution: Use low-order splines.

However, there is more in the theory, old and recent ...

Don't Preserve Polynomials

- ▶ **Féjer**: Use $M(N) = 2N - 1$, with zero derivative conditions

$$p'_{2N-1}(x_i; N) = 0.$$

- ▶ Converges for **all** continuous functions if x_N are zeros of Chebyshev polynomial!
- ▶ **Berman**: **Diverges** for equi-spaced points (Runge phenomenon).
- ▶ **Bernstein**: Give up **interpolation** and use

$$p_{N-1}(x) = \frac{1}{2^{N-1}} \sum_{k=0}^{N-1} \binom{N-1}{k} f(x_{k+1}; N) (1+x)^k (1-x)^{N-1-k}.$$

Converges for **all** continuous functions at equi-spaced points!

A Negative Result

- ▶ **Lozinskii and Kharshiladza.** Let U_N linearly map f on $[-1, 1]$ to a polynomial of degree N . Then $U_N(f)$ **cannot** converge for all continuous functions in any $1 \leq p \leq \infty$ norm, if U_N **preserves polynomials** of degree $\leq N$.
- ▶ **Timan.** If a triangular weighting scheme is used to damp the coefficients, convergence can be recovered (we lose polynomial preservation **and** interpolation).
- ▶ However, one can do better ...

A Positive Result

Erdős and **Szabados**. For every $\epsilon > 0$,

- ▶ there exists a polynomial of degree $\frac{\pi}{2}N(1 + \epsilon)$
- ▶ that interpolates the given continuous function at N equi-spaced points on $[-1, 1]$,
- ▶ and these polynomials converge uniformly to f ,
- ▶ with error that is of the same order of magnitude as that of the **best approximating polynomial** of degree $\frac{\pi}{2}N(1 + \frac{\epsilon}{3})$.

However

- ▶ Proof is non-constructive
- ▶ Generalization requires sample points to be dense in $[-1, 1]$

Our Approach

We propose

- ▶ **linear** approach to construct
- ▶ an **interpolating** polynomial
- ▶ converges at **limit points** of the sample points
- ▶ does not preserve polynomials
- ▶ **no** constraint on interpolation points
- ▶ works in **higher dimensions**
- ▶ **any** basis with nice Sobolev norm

Polynomial Preservation

- ▶ Not a good idea in theory & practice
- ▶ Do not want to recover a 1000 degree polynomial from a “straight” line

Choosing The Basis

Chebyshev polynomials

$$T_0(x) = 1$$

$$T_1(x) = x$$

$$T_{n+1}(x) = 2xT_n(x) - T_{n-1}(x)$$

or

$$T_n(x) = \cos(n \cos^{-1} x), \quad -1 \leq x \leq 1$$

We will represent our polynomials as

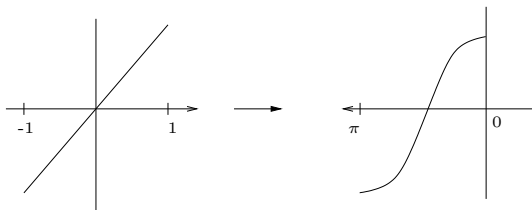
$$p_M = \sum_{n=0}^M a_n T_n$$

Gautschi. This is a reasonably stable representation.

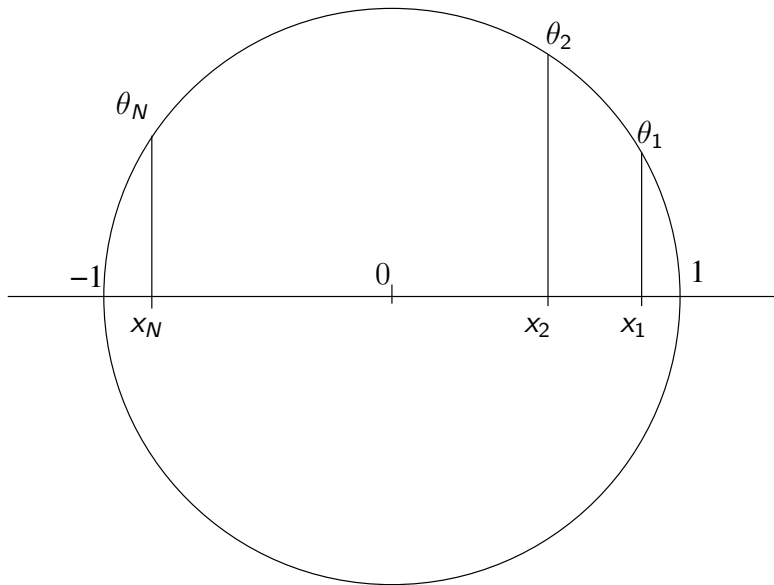
The Circle

- ▶ $\Gamma =$ unit circle in \mathcal{R}^2
- ▶ $\cos \theta = x$ maps Γ onto $[-1, 1]$
- ▶ f smooth on $[-1, 1] \equiv f \circ \cos$ smooth on Γ

$$\begin{aligned}\frac{d}{d\theta} f(\cos \theta) &= -f'(\cos \theta) \sin \theta \\ \frac{d^2}{d\theta^2} f(\cos \theta) &= f''(\cos \theta) \sin^2 \theta - f'(\cos \theta) \cos \theta \\ &\vdots = \vdots\end{aligned}$$



Cosine Map



Fourier Cosine Series

$$f(x) = f(\cos \theta) = \sum_{n=0}^{\infty} \hat{f}_n \cos(n\theta)$$

$$= \sum_{n=0}^{\infty} \hat{f}_n T_n(x)$$

$$\hat{f}_0 = \frac{1}{\pi} \int_0^{\pi} f(\cos \theta) d\theta$$

$$\hat{f}_n = \frac{2}{\pi} \int_0^{\pi} f(\cos \theta) \cos(n\theta) d\theta$$

Hölder Continuous

- ▶ α -Hölder norm of f :

$$\sup_{x,y \in [-1,1]} \frac{|f(x) - f(y)|}{|x - y|^\alpha}$$

- ▶ $C^{k+\alpha}(S) \equiv k$ -th derivative is α -Hölder continuous on S
- ▶ If $f \in C^{k+\alpha}[-1, 1]$ then

$$\hat{f}_n = O\left(\frac{1}{n^{k+\alpha}}\right)$$

- ▶ **Bernstein.** If $f \in C^\alpha[-1, 1]$ with $s > \frac{1}{2}$, then \hat{f}_n is absolutely summable.

Sobolev Spaces

If $f(\theta) = \sum_{n=0}^{\infty} \hat{f}_n \cos(n\theta)$, then

$$f'(\theta) = -\sum_{n=0}^{\infty} n \hat{f}_n \sin(n\theta)$$

$$f''(\theta) = \sum_{n=0}^{\infty} n^2 \hat{f}_n \cos(n\theta)$$

The Sobolev space H_s contains f if

$$\hat{f}_0^2 + \sum_{n=1}^{\infty} n^{2s} \hat{f}_n^2 < \infty.$$

Sobolev spaces and Hölder norms. $C^s \subseteq H_s \subseteq C^{s-\frac{1}{2}}$.

Damping Oscillations

- ▶ **Féjer**: oscillations in between interpolation nodes (Runge phenomenon) can be damped by controlling derivatives.
- ▶ Numerically difficult in spatial domain.

Key observations

- ▶ Easier for $(f \circ \cos)'$ than f' .
- ▶ Control derivative in L_2 rather than point-wise like Féjer.

Optimization Problem

Minimum Sobolev norm method: Choose $a_{M;n}$ to be the optimal solution of

$$\min_{a_{N;n}} a_{N;0}^2 + \sum_{n=1}^{M(N)} n^{2s} a_{N;n}^2$$

such that

$$\sum_{n=0}^{M(N)} a_{N;n} T_n(x_i;N) = f(x_i;N), \quad 1 \leq i \leq N,$$

with $s > \frac{1}{2}$.

Recommendations

▶ $s = 1.5$

▶ $M(N) = 1.5 \left\lceil \frac{\pi}{\min_{i \neq j} |\cos^{-1}(x_i;N) - \cos^{-1}(x_j;N)|} \right\rceil$

Convergence

Theorem

- ▶ Let x_N be a sequence of N distinct points in $[-1, 1]$.
- ▶ Let x be a limit point of the x_N .
- ▶ Let $f \in H_s[-1, 1]$ with $s > \frac{1}{2}$.
- ▶ Let c be a constant which depends only on x_N and s .
- ▶ Let

$$M(N) = c \left[\frac{1}{\min_{i \neq j} |\cos^{-1}(x_{i;N}) - \cos^{-1}(x_{j;N})|} \right].$$

- ▶ Let $p_{M(N)}$ denote the optimal Sobolev s -norm interpolating polynomial for f at x_N .

Then, c can be chosen such that

$$\lim_{N \uparrow \infty} p_{M(N)}(x) = f(x),$$

for all $f \in H_s[-1, 1]$.

Convergence ...

- ▶ Proof generalizes to higher dimensions: $[-1, 1]^d$
- ▶ Proof generalizes to other bases with suitable Sobolev p -norms
- ▶ Convergence is **independent** of point distribution
- ▶ H_s for $s \leq \frac{1}{2}$ contains dis-continuous functions
- ▶ Proof is very technical; uses Riesz–Thorin interpolation theorem and Marcinkiewicz–Zygmund type inequalities
- ▶ Draft tutorial in one dimension is available
- ▶ Much simpler to ignore tightness of $M(N)$ and concentrate on point distribution independent convergence

Convergence for $M(N) = \infty$ and $s > \frac{3}{2}$

Theorem

Let p_N denote the optimal *infinite* order polynomial that interpolates $f \in H_s[-1, 1]$ with $s > \frac{3}{2}$ at the given N distinct points $-1 \leq x_{i;N} \leq 1$ for $1 \leq i \leq N$. Let x be a limit point for the x_N . Then $\lim_{N \uparrow \infty} p_N(x) = f(x)$.

- ▶ Convergence is **independent** of point distribution.
- ▶ First derivative of f must be Hölder continuous with exponent greater than $\frac{1}{2}$.
- ▶ If $s = 2$ there is an exact computational procedure to find $a_{N;n}$.
- ▶ There is an effective truncation procedure; but interpolation property will become approximate rather than exact.

Proof

- ▶ The Fourier Cosine series is a feasible solution. Hence

$$a_{N;0}^2 + \sum_{n=1}^{\infty} n^{2s} a_{N;n}^2 \leq \hat{f}_0^2 + \sum_{n=1}^{\infty} n^{2s} \hat{f}_n^2 < \infty.$$

- ▶ By Cauchy–Schwartz

$$\begin{aligned} \sum_{n=1}^{\infty} n |a_{N;n}| &= \sum_{n=1}^{\infty} \frac{1}{n^{s-1}} n^s |a_{N;n}| \\ &\leq \sqrt{\sum_{n=1}^{\infty} \frac{1}{n^{2(s-1)}}} \sqrt{\sum_{n=1}^{\infty} n^{2s} a_{N;n}^2} \\ &< \infty, \end{aligned}$$

if $s > \frac{3}{2}$.

Proof ...

- ▶ $\|(p_N \circ \cos)'\|_\infty$ is uniformly bounded
- ▶ $\|p_N \circ \cos\|_\infty$ is uniformly bounded
- ▶ **Ascoli–Arzelà**: there is a uniformly converging sub-sequence
- ▶ For some sub-sequence p_{N_j}

$$\lim_{j \uparrow \infty} \|p_{N_j} - p\|_\infty = 0$$

- ▶ For some sub-sub-sequence $x_{N_{j_k}}$

$$\lim_{k \uparrow \infty} x_{i_k; N_{j_k}} = x$$

- ▶ p is continuous; f is continuous

Proof ...

$$\begin{aligned} |p(x) - f(x)| &= \lim_{k \uparrow \infty} |p(x_{i_k}; N_{j_k}) - f(x_{i_k}; N_{j_k})| \\ &= \lim_{k \uparrow \infty} |p(x_{i_k}; N_{j_k}) - p_{N_{j_k}}(x_{i_k}; N_{j_k})| \\ &\leq \lim_{k \uparrow \infty} \|p - p_{N_{j_k}}\|_{\infty} \\ &= 0 \end{aligned}$$

- ▶ There is nothing special about the sub-sequence p_{N_j} and its limit point p
- ▶ Therefore, every limit point of p_N must satisfy $p(x) = f(x)$
- ▶ In other words, $\lim_{N \uparrow \infty} p_N(x) = f(x)$

QED

Convergence for $M = \infty$ and $s > \frac{1}{2}$

- ▶ Only a little more effort ...
- ▶ Exact computational procedure for $s = 1$
- ▶ A lot more effort, but still elementary analysis, can handle $M = O(N^2)$
- ▶ Handling $M = O(N)$ is very technical
- ▶ Extendable to piece-wise smooth functions, if points of discontinuity are not limit points
- ▶ In practice the *opposite* works very well

Runge Phenomenon Banished

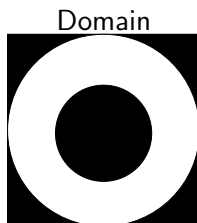
- ▶ $f(x) = (1 + 100x^2)^{-1}$
- ▶ N equi-spaced points on $[-1, 1]$ excluding boundary
- ▶ $M(N) = 2N$
- ▶ Larger s is better in this case, but the condition number of the constraint equations also increases

Maximum point-wise error between f and the interpolating polynomial:

| N | $s = 1.5$ | $s = 2.5$ |
|-----|-------------------|-------------------|
| 15 | $7 \cdot 10^{-2}$ | $7 \cdot 10^{-2}$ |
| 30 | $2 \cdot 10^{-2}$ | $2 \cdot 10^{-2}$ |
| 60 | $8 \cdot 10^{-4}$ | $3 \cdot 10^{-4}$ |
| 120 | $3 \cdot 10^{-4}$ | $4 \cdot 10^{-6}$ |
| 240 | $1 \cdot 10^{-4}$ | $7 \cdot 10^{-7}$ |
| 480 | $3 \cdot 10^{-5}$ | $1 \cdot 10^{-7}$ |
| 960 | $8 \cdot 10^{-6}$ | $1 \cdot 10^{-8}$ |

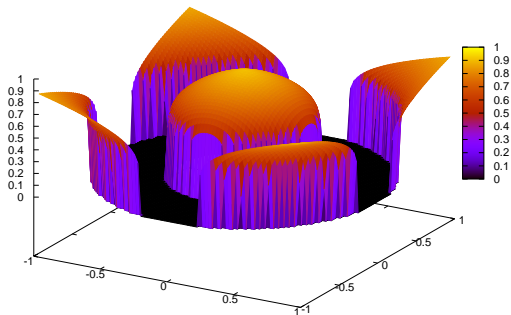
Difficult 2D Interpolation

- ▶ $f(r, \theta) = (|r - 0.5| |r - 1|)^{\frac{1}{8}}$
- ▶ Domain is black region in figure below
- ▶ Curved line singularities on multiply connected domain
- ▶ 156 equi-spaced samples in domain
- ▶ 1929 2D Chebyshev polynomials with $s = 1.5$



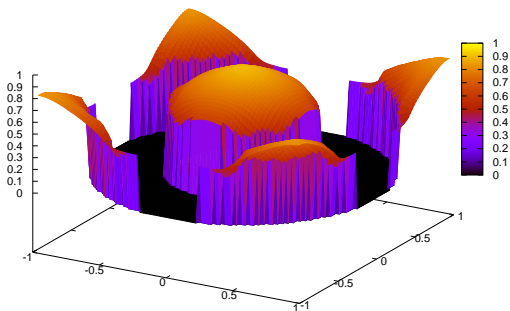
Difficult 2D Interpolation ...

Original function



Difficult 2D Interpolation ...

Interpolant



Rapid Local Convergence

- ▶ 8th-root singularity is not covered by our theorem
- ▶ In 1D rate of convergence at a point is only based on the local smoothness of the function
- ▶ $f(x) = |x|^{\frac{1}{8}}$ on $[-1, 1]$.
- ▶ N equi-spaced samples; $M(N) = 6N$ and $s = 1.5$
- ▶ Errors between f and interpolant at $x = 0$ and $x = 0.5$

| N | $x = 0$ | $x = 0.5$ |
|------|-------------------|-------------------|
| 16 | $7 \cdot 10^{-1}$ | $7 \cdot 10^{-5}$ |
| 32 | $6 \cdot 10^{-1}$ | $3 \cdot 10^{-6}$ |
| 64 | $6 \cdot 10^{-1}$ | $1 \cdot 10^{-6}$ |
| 128 | $5 \cdot 10^{-1}$ | $2 \cdot 10^{-7}$ |
| 256 | $5 \cdot 10^{-1}$ | $2 \cdot 10^{-7}$ |
| 512 | $5 \cdot 10^{-1}$ | $4 \cdot 10^{-8}$ |
| 1024 | $4 \cdot 10^{-1}$ | $2 \cdot 10^{-8}$ |

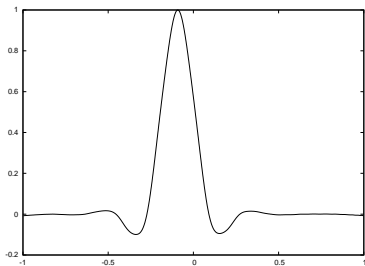
- ▶ Seems to be true in higher dimensions too

Interpolatory Kernels

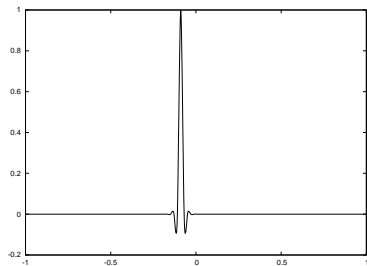
Due to linearity

$$p_{M(N)}(x) = \sum_{i=1}^N f(x_{i;N}) l_{i;N;M(N)}(x)$$

$l_{i;N;M(N)}$ is a polynomial of degree M that depends on x_N and s .



$l_{5;10;60}$



$l_{46;100;600}$

Speed

- ▶ In 1D there are traditional “matrix-free” methods
- ▶ We have fast algorithms instead

In Matrix Language

$$V_{N;M}(x_N) = \begin{pmatrix} 1 & \cos(\theta_{1;N}) & \cos(2\theta_{1;N}) & \cdots & \cos(M\theta_{1;N}) \\ 1 & \cos(\theta_{2;N}) & \cos(2\theta_{2;N}) & \cdots & \cos(M\theta_{2;N}) \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ 1 & \cos(\theta_{N;N}) & \cos(2\theta_{N;N}) & \cdots & \cos(M\theta_{N;N}) \end{pmatrix}$$
$$D_s = \text{diag}(1^s \quad 2^s \quad 3^s \quad \cdots)$$

Optimization problem

$$\min_{a_N} \|D_s a_N\|_2, \quad \text{such that} \quad V_{N;M}(x_N) a_N = f(x_N)$$

Optimal solution

$$a_N = D_s^{-1} (V_{N;M}(x_N) D_s^{-1})^\dagger f(x_N)$$

Optimal polynomial

$$p_M(x) = V_{N;M}(x) D_s^{-1} (V_{N;M}(x_N) D_s^{-1})^\dagger f(x_N)$$

Matrix Structure

$$(V_N D_s^{-1})^\dagger = D_s^{-1} V_N^T (V_N D_s^{-2} V_N^T)^{-1}$$

Displacement Structure

$$(V_N D_s^{-1})(D_s(I + Z^2)) - (2X_N)(V_N D_s^{-1})(D_s Z) = \text{rank } 2$$

Sequentially Semi-Separable Structure

Numerical rank of off-diagonal blocks of $V_{N;M} D_s^{-2} V_{N;M}^T$ with $s = 1.5$ for N equi-spaced points.

| N | M | 10^{-8} | 10^{-10} |
|-------|--------|-----------|------------|
| 320 | 1,514 | 7 | 10 |
| 640 | 3,020 | 7 | 10 |
| 1,280 | 6,038 | 7 | 10 |
| 2,560 | 12,068 | 7 | 10 |

Exact SSS

If $M = \infty$ then $V_N D_s^{-2} V_N^T$ has exact Hankel ranks:

- ▶ $s = 1 \Rightarrow$ Hankel rank = 3
- ▶ $s = 2 \Rightarrow$ Hankel rank = 5

Summary

Minimum Sobolev 2-norm methods in Chebyshev basis solve the polynomial interpolation problem in \mathcal{R}^d , in a distribution agnostic manner with good convergence properties

Future Work

- ▶ Can work with other bases: for example, interpolatory wavelet expansions; compressed sensing?
- ▶ Shows rapid local convergence: proof? meshless methods?
- ▶ Works as singularity detector on incomplete samples: applications to signal and image processing
- ▶ Interpolation on manifolds using Laplace–Beltrami eigenfunctions
- ▶ Works for boundedly invertible operators: discretization of partial differential and integral equations

THANK YOU!